## JRCW450U Orca\* Series: DC-DC Converter Power Modules

36-75 Vdc Input; 48Vdc Output; 450W Output

## **RoHS Compliant**



## **Applications**

- RF Power Amplifier
- Wireless Networks
- Switching Networks

### **Options**

- Output OCP/OVP auto restart
- Shorter pins
- Unthreaded heat sink holes

### **Features**

- Compliant to RoHS II EU Directive 2011/65/EC (-Z versions)
- Compliant to REACH Directive (EC) No 1907/2006
- High power density: 166 W/in<sup>3</sup>
- Very high efficiency: >94% Typ at Full Load
- Industry standard half-brick pin-out
- Low output ripple and noise
- Industry standard half-brick footprint 57.7mm x 60.7mm x 12.8mm (2.27" x 2.39" x 0.504")
- Remote Sense
- 2:1 input voltage range
- Single tightly regulated output
- Constant switching frequency
- Constant Current Overcurrent limit
- Latch after short circuit fault shutdown
- Over temperature protection auto restart
- Output voltage adjustment trim, 28.8V<sub>dc</sub> to 57.6V<sub>dc</sub>
- Wide operating case temperature range (-40°C to 100°C)
- CE mark meets 2006/95/EC directives§
- ANSI/UL# 60950-1, 2nd Ed. Recognized, CSA<sup>†</sup> C22.2 No. 60950-1-07 Certified, and VDE<sup>‡</sup> 0805-1 (EN60950-1, 2nd Ed.) Licensed
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

## **Description**

The JRCW450U Orca series of dc-dc converters are a new generation of isolated, very high efficiency DC/DC power modules providing up to 450W output power in an industry standard half-brick size footprint, which makes it an ideal choice for high voltage and high power applications. Threaded-through holes are provided to allow easy mounting or addition of a heat sink for high-temperature applications. The output is fully isolated from the input, allowing versatile polarity configurations and grounding connections.

<sup>\*</sup> Trademark of the General Electric Company

<sup>#</sup> UL is a registered trademark of Underwriters Laboratories, Inc.

<sup>†</sup> CSA is a registered trademark of Canadian Standards Association.

VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

<sup>\*\*</sup> ISO is a registered trademark of the International Organization of Standards

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## **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage					
Continuous	All	V <sub>IN</sub>	-0.3	80	V <sub>dc</sub>
Transient, operational (≤100 ms)	All	V <sub>IN,trans</sub>	-0.3	100	$V_{dc}$
Operating Case Temperature (See Thermal Considerations section, Figure 16)	All	Tc	-40	100	°C
Storage Temperature	All	T <sub>stg</sub>	-55	125	°C
I/O Isolation Voltage: Input to Case, Input to Output	All	_	_	1500	$V_{dc}$
Output to Case	All	_	_	500	$V_{dc}$

## **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage (see Figure 12 for V <sub>IN MIN</sub> when using trim-up feature)	All	V <sub>IN</sub>	36	48	75	V <sub>dc</sub>
Maximum Input Current						
(V <sub>IN</sub> =36V to 75V, Io=Io, max)	All	I <sub>IN,max</sub>			14.0	A <sub>dc</sub>
Inrush Transient	All	I2t			2	A <sup>2</sup> s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 12µH source impedance; V <sub>IN</sub> =0V to 75V, I <sub>O</sub> = I <sub>Omax</sub> ; see Figure 7)	All				20	mA <sub>p-p</sub>
Input Ripple Rejection (120Hz)	All			40		dB

#### CAUTION: This power module is not internally fused. An input line fuse must always be used.

This power module can be used in a wide variety of applications, ranging from simple standalone operation to being an integrated part of complex power architecture. To preserve maximum flexibility, internal fusing is not included. Always use an input line fuse, to achieve maximum safety and system protection. The safety agencies require a time-delay or fast-acting fuse with a maximum rating of 25 A in the ungrounded input connection (see Safety Considerations section). Based on the information provided in this data sheet on inrush energy and maximum dc input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data sheet for further information.

# JRCW450U Orca Series; DC-DC Converter Power Modules

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# **Electrical Specifications** (continued)

Device	Symbol	Min	Тур	Max	Unit
All	V <sub>O, set</sub>	47.0	48	49.0	$V_{dc}$
All	Vo	47.0	_	49.0	$V_{dc}$
All All		_ _ _	0.1 0.1 0.25	0.2 0.2 0.5	%V <sub>o,set</sub> %V <sub>o,set</sub> %V <sub>o,set</sub>
All All		_ _	100 300	125 400	mV <sub>rms</sub> mV <sub>pk-pk</sub>
All	Co	440		6500	μF
All	P <sub>O,max</sub>	_	_	450	W
All	lo	0		9.4	A <sub>dc</sub>
All	I <sub>O, lim</sub>	11.0	_	12.2	A <sub>dc</sub>
All	I <sub>O, sc</sub>			15	Arms
All	η	93.5	94.0	_	%
	f <sub>sw</sub>	_	180	_	kHz
All	V <sub>pk</sub> t <sub>s</sub>	_ _ _	2 1.5 2	3 — 3	%V <sub>0, set</sub> ms %V <sub>0, set</sub> ms
	All	All Vo, set  All Vo  All All All All All All All Co  All Po,max  All Io, lim  All Io, sc  All I The set All Io, sc  All Vpk  ts	All Vo, set 47.0  All Vo 47.0  All — — — — — — — — — — — — — — — — — —	All V <sub>O, set</sub> 47.0 48  All V <sub>O</sub> 47.0 —  All — 0.1 All — 0.1 All — 0.25  All — 100 All — 300 All — 300 All P <sub>O,max</sub> — — — All I <sub>O</sub> 0  All I <sub>O, sc</sub> — 11.0  All η 93.5 94.0  All γ <sub>pk</sub> — 2 t <sub>s</sub> — 1.5 V <sub>pk</sub> — 2	All Vo, set 47.0 48 49.0  All Vo 47.0 — 49.0  All — 0.1 0.2 0.1 0.2 0.2 0.5  All — 100 125 0.5  All — 300 400  All Po,max — 450  All Io 0 9.4  All Io, sc 15  All η 93.5 94.0 —  All γρ <sub>k</sub> — 2 3 3 1.5 —  V <sub>pk</sub> — 2 3 3

 $<sup>^1</sup>$ Note: use a minimum 2 x 220uF output capacitor. Recommended capacitor is Nichicon CD series, 220uF/35V. If the ambient temperature is less than -20°C, use more than 3 of recommended minimum capacitors. When starting into maximum external capacitor, do not simultaneously apply a Constant Current electronic load set to greater than 0.5 x  $l_{oMAX}$  or delay application of full CC load until  $V_o > 1.0$ V.

### **Isolation Specifications**

Parameter	Symbol	Min	Тур	Max	Unit
Isolation Capacitance	Ciso		15	_	nF
Isolation Resistance	Riso	10	_	_	ΜΩ

## **General Specifications**

Parameter	Device	Symbol	Min	Тур	Max	Unit
Calculated Reliability based upon Telcordia SR-332 Issue 3:	All	FIT		136.3		109/Hours
Method I Case 3 (Io=80%Io, max, T <sub>A</sub> =40°C, airflow = 200 lfm, 90% confidence)	All	MTBF		7,338,052		Hours
Weight	All		68	76.4	84	g
Weight	All		2.40	2.69	2.96	OZ.

# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

## **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Remote On/Off Signal Interface $(V_{IN}=V_{IN,min}$ to $V_{IN,max}$ ; open collector or equivalent, Signal referenced to $V_{IN}$ terminal)						
Negative Logic: device code suffix "1" Logic Low = module On, Logic High = module Off						
Positive Logic: No device code suffix required Logic Low = module Off, Logic High = module On						
Logic Low - Remote On/Off Current Logic Low - On/Off Voltage Logic High Voltage - (Typ = Open Collector) Logic High maximum allowable leakage current	All All All	Ion/off Von/off Von/off Ion/off	0 4 —		1.0 0.8 5 50	mA V <sub>dc</sub> V <sub>dc</sub> μA
Turn-On Delay and Rise Times (Vin=V <sub>innom</sub> , Io=Io, mox, 25C)						
Case 1: $T_{delay}$ = Time until $V_0$ = 10% of $V_{0,set}$ from application of $V_{in}$ with Remote On/Off set to ON	All	T <sub>delay</sub>	100	120	150	ms
Case 2: $T_{delay}$ = Time until $V_0$ = 10% of $V_{0,set}$ from application of Remote On/Off from Off to On with $V_{in}$ already applied for at least one second.	All	$T_{delay}$	15	20	25	ms
$T_{\text{rise}}\!=\!$ time for $V_0$ to rise from 10% of $V_{0,\text{set}}$ to 90% of $V_{0,\text{set}}.$	All	$T_{rise}$	40	60	80	
Synchronous Rectifier Activation Level and Delay* Minimum Iout to activate synch rectifier mode		lout,sync	2.4			А
Minimum time to activate synch rectifier mode (IouT> IOUT,SYNC)		$T_{SYNC}$	1			ms
Output Voltage Overshoot (Io=80% of Io, max, Ta=25°C)					3	% V <sub>O, set</sub>
Output Voltage Adjustment (See Feature Descriptions):						
Output Voltage Remote-sense Range (only for No Trim or Trim down application )	All	$V_{\text{sense}}$	_	_	2	$%V_{o,nom}$
Output Voltage Set-point Adjustment Range (trim)	All	$V_{\text{trim}}$	28.8		57.6	$V_{dc}$
Output Overvoltage Protection (T <sub>A</sub> =25C)	All	$V_{O, limit}$	60	_	65	$V_{dc}$
Over Temperature Protection	All	$T_{ref}$	108	115	120	°C
(See Feature Descriptions, Figure 16)						
Input Under Voltage Lockout		V <sub>IN, UVLO</sub>				
Turn-on Threshold	All		33	35	36	V <sub>dc</sub>
Turn-off Threshold	All All		30 2.5	32 3	33 3.5	V <sub>dc</sub>
Hysteresis Input Over voltage Lockout	All	V <sub>IN, OVLO</sub>	2.5	3	3.5	V <sub>dc</sub>
Turn-on Threshold	All	VIIV, OVEO	77	80	82	V <sub>dc</sub>
Turn-off Threshold	All		80	83.5	86	V <sub>dc</sub>
Hysteresis	All		2.5	3	5	$V_{dc}$

<sup>\*</sup> Note: Module has internal circuit that inhibits output synchronous rectifier mode, during module startup, until IouT. SYNC for time> TsynC. Once output synchronous mode is activated, module remains in synchronous rectifier mode, even if load is reduced to OA, until module output is turned off using on/off pin or loss of input voltage.

# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

#### **Characteristic Curves**

The following figures provide typical characteristics for the JRCW450U (48V, 9.4A) at 25°C. The figures are identical for either positive or negative Remote On/Off logic.

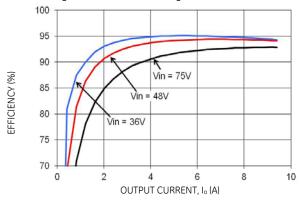


Figure 1. Converter Efficiency versus Output Current.

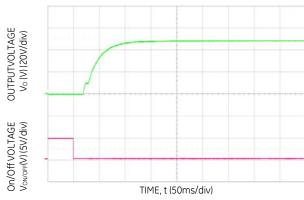


Figure 4. Typical Start-Up Using negative Remote On/Off;  $C_{o,\text{ext}} = 440 \mu F$ .

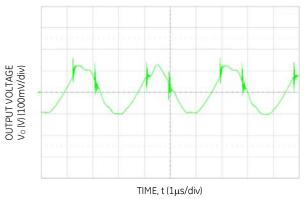


Figure 2. Typical Output Ripple and Noise at Room Temperature and 48Vin;  $I_o = I_{o,max}$ ;  $C_{o,ext} = 440 \mu F$ .

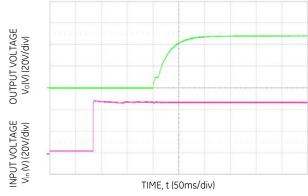


Figure 5. Typical Start-Up from  $V_{IN},$  on/off enabled prior to  $V_{IN}$  step;  $C_{o,ext}$  =  $470\mu F.$ 

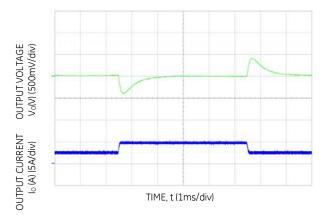


Figure 3. Dynamic Load Change Transient Response from 25% to 50% to 25% of Full Load at Room Temperature and 48 Vin; 0.1A/uS,  $C_{o,ext}$  = 440 $\mu$ F.

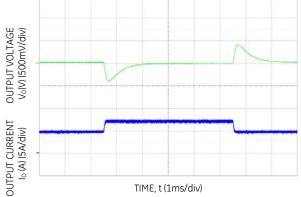
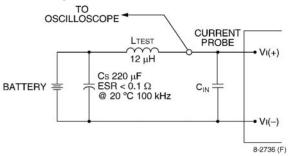


Figure 6. Dynamic Load Change Transient Response from 50 % to 75% to 50% of Full Load at Room Temperature and 48 Vin; 0.1A/uS,  $C_{o,ext} = 440\mu F$ .

# JRCW450U Orca Series; DC-DC Converter Power Modules

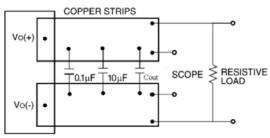
36-75 Vdc Input; 48.0Vdc Output; 450W Output

## **Test Configurations**



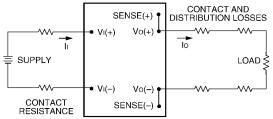
Note: Measure the input reflected-ripple current with a simulated source inductance (LTEST) of 12 µH. Capacitor CS offsets possible battery impedance. Measure the current, as shown above.

Figure 7. Input Reflected Ripple Current Test Setup.



Note: Use a  $C_{out}$  (470  $\mu$ F Low ESR aluminum or tantalum capacitor typical), a 0.1  $\mu$ F ceramic capacitor and a 10  $\mu$ F ceramic capacitor, and Scope measurement should be made using a BNC socket. Position the load between 51 mm and 76 mm (2 in. and 3 in.) from the module

Figure 8. Output Ripple and Noise Test Setup.



8-3300 (E)

Note: All measurements are taken at the module terminals. When socketing, place Kelvin connections at module terminals to avoid measurement errors due to socket contact resistance.

$$\eta \ = \ \left( \frac{[V_O(^+) - V_O(^-)]I_O}{[V_I(^+) - V_I(^-)]I_I} \right) \times 100 \ \%$$

Figure 9. Output Voltage and Efficiency Test Setup.

#### **Design Considerations**

#### Input Source Impedance

The power module should be connected to a low ac-impedance source. A highly inductive source impedance can affect the stability of the power module. For the test

configuration in Figure 7, a 470 $\mu$ F Low ESR aluminum capacitor,  $C_{IN}$ , mounted close to the power module helps ensure the stability of the unit.

Consult the factory for further application guidelines.

#### **Output Capacitance**

The JRCW450U power module requires a minimum output capacitance of 440 $\mu$ F Low ESR aluminum capacitor, C<sub>out</sub> to ensure stable operation over the full range of load and line conditions, see Figure 8. If the ambient temperature is under -20C, it is required to use at least 3 pcs of minimum capacitors in parallel. In general, the process of determining the acceptable values of output capacitance and ESR is complex and is load-dependent.

#### **Safety Considerations**

For safety-agency approval of the system in which the power module is used, the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standard, i.e., UL 60950-1, 2nd Ed., CSA No. 60950-1 2nd Ed., and VDE0805-1 EN60950-1, 2nd Ed.

For end products connected to –48V dc, or –60Vdc nominal DC MAINS (i.e. central office dc battery plant), no further fault testing is required. \*Note: –60V dc nominal battery plants are not available in the U.S. or Canada.

For all input voltages, other than DC MAINS, where the input voltage is less than 60V dc, if the input meets all of the requirements for SELV, then:

 The output may be considered SELV. Output voltages will remain within SELV limits even with internally-generated non-SELV voltages. Single component failure and fault tests were performed in the power converters.

One pole of the input and one pole of the output are to be grounded, or both circuits are to be kept floating, to maintain the output voltage to ground voltage within ELV or SELV limits. However, SELV will not be maintained if  $V_1(+)$  and  $V_0(+)$  are grounded simultaneously.

For all input sources, other than DC MAINS, where the input voltage is between 60 and 75V dc (Classified as TNV-2 in Europe), the following must be meet, if the converter's output is to be evaluated for SELV:

- The input source is to be provided with reinforced insulation from any hazardous voltage, including the ac mains.
- One Vi pin and one Vo pin are to be reliably earthed, or both the input and output pins are to be kept floating.
- Another SELV reliability test is conducted on the whole system, as required by the safety agencies, on the combination of supply source and the subject module to verify that under a single fault, hazardous voltages do not appear at the module's output.

# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

### **Safety Considerations (continued)**

All flammable materials used in the manufacturing of these modules are rated 94V-0, or tested to the UL60950 A.2 for reduced thickness.

The input to these units is to be provided with a maximum 25 A fast-acting or time-delay fuse in the ungrounded input connection

To ensure safety compliance, the temperatures at Tref1, Tref2, or Tref3 should (Figure 16) not exceed the limits as specified in this table for Vin = 36 to 75V.

Tref1 or Tref2	Tref3
90°C	130°C

## **Feature Description**

#### Remote On/Off

Two remote on/off options are available. Positive logic turns the module on during a logic high voltage on the ON/OFF pin, and off during a logic low. Negative logic remote On/Off, device code suffix "1", turns the module off during a logic high and on during a logic low.

To turn the power module on and off, the user must supply a switch (open collector or equivalent) to control the voltage ( $V_{\text{on/off}}$ ) between the ON/OFF terminal and the  $V_{\text{IN}}(-)$  terminal (see Figure 10). Logic low is  $0V \leq V_{\text{on/off}} \leq 0.8V$ . The maximum  $I_{\text{on/off}}$  during a logic low is 1mA, the switch should be maintain a logic low level whilst sinking this current.

During a logic high, the typical maximum  $V_{on/off}$  generated by the module is 5V, and the maximum allowable leakage current at  $V_{on/off} = 5V$  is  $50\mu A$ .

If not using the remote on/off feature:

For positive logic, leave the ON/OFF pin open.

For negative logic, short the ON/OFF pin to  $V_{IN}(-)$ .

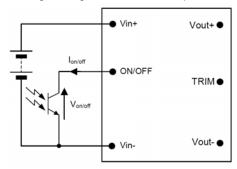


Figure 10. Circuit configuration for using Remote On/Off Implementation.

#### **Overcurrent Protection**

To provide protection in a fault output overload condition, the module is equipped with internal current limiting protection circuitry, and can endure continuous overcurrent by providing constant current output, for up to 4 seconds, as long as the

output voltage is greater than  $V_{\text{trimMIN}}$ . If the load resistance is too low to support  $V_{\text{trimMIN}}$  in an overcurrent condition or a short circuit load condition exists, the module will shut down immediately.

A latching shutdown option is standard. Following shutdown, the module will remain off until the module is reset by either cycling the input power or by toggling the on/off pin for one second

An auto-restart option (4) is also available in a case where an auto recovery is required. If overcurrent greater than 12A persists for few milli-seconds, the module will shut down and auto restart until the fault condition is corrected. If the output overload condition still exists when the module restarts, it will shut down again. This operation will continue indefinitely, until the overcurrent condition is corrected.

#### **Over Voltage Protection**

The output overvoltage protection consists of circuitry that monitors the voltage on the output terminals. If the voltage on the output terminals exceeds the over voltage protection threshold, then the module will shut down and latch off. The overvoltage latch is reset by either cycling the input power for one second or by toggling the on/off signal for one second. The protection mechanism is such that the unit can continue in this condition until the fault is cleared.

An auto-restart option (4) is also available in a case where an auto recovery is required.

#### Remote sense

Remote sense minimizes the effects of distribution losses by regulating the voltage at the remote-sense connections (see Figure 11). For No Trim or Trim down application, the voltage between the remote-sense pins and the output terminals must not exceed the output voltage sense range given in the Feature Specifications table i.e.:

 $[V_o(+)-V_o(-)]$  - [SENSE(+) -  $SENSE(-)] \le 2\%$  of  $V_{o,nom}$ 

The voltage between the Vo(+) and Vo(-) terminals must not exceed the minimum output overvoltage shut-down value indicated in the Feature Specifications table. This limit includes any increase in voltage due to remote-sense compensation and output voltage set-point adjustment (trim). See Figure 11. If not using the remote-sense feature to regulate the output at the point of load, then connect SENSE(+) to  $V_0(+)$  and SENSE(-) to  $V_0(-)$  at the module. Although the output voltage can be increased by both the remote sense and by the trim, the maximum increase for the output voltage is not the sum of both. The maximum increase is the larger of either the remote sense or the trim. The amount of power delivered by the module is defined as the voltage at the output terminals multiplied by the output current. When using remote sense and trim: the output voltage of the module can be increased, which at the same output current would increase the power output of the module. Care should be taken to ensure that the maximum output power of the module remains at or below the maximum rated power.

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36-75 Vdc Input; 48.0Vdc Output; 450W Output

## Feature Description (continued)

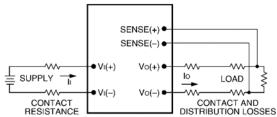


Figure 11. Effective Circuit Configuration for Single-Module Remote-Sense Operation Output Voltage.

#### **Output Voltage Programming**

Trimming allows the user to increase or decrease the output voltage set point of a module. Trimming down is accomplished by connecting an external resistor between the TRIM pin and the SENSE(-) pin. Trimming up is accomplished by connecting external resistor between the SENSE(+) pin and TRIM pin. The trim resistor should be positioned close to the module. Certain restrictions apply to the input voltage lower limit when trimming the output voltage to the maximum. See Figure 12 for the allowed input to output range when using trim. If not using the trim down feature, leave the TRIM pin open.

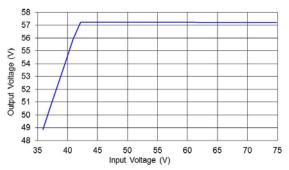


Figure 12. Output Voltage Trim Limits vs. Input Voltage.

#### Trim Down - Decrease Output Voltage

With an external resistor ( $R_{adj\_down}$ ) between the TRIM and SENSE(-) pins, the output voltage set point ( $V_{o,adj}$ ) decreases (see Figure 13). The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta\%$ .

For output voltages:  $V_{O,nom} = 48V$ 

Without -T Option	With -T Option
$R_{adj\_down} = \left(\frac{100}{\Delta\%} - 2\right) k\Omega$	$R_{adj\_down} = \left(\frac{1000}{\Delta\%} - 11\right) k\Omega$

Where, 
$$\Delta\% = \left|\frac{V_{o,\,nom} - V_{desired}}{V_{o,\,nom}}\right| \times 100$$
 
$$V_{desired} = \text{Desired output voltage set point (V)}.$$

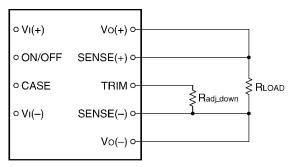


Figure 13. Circuit Configuration to Decrease Output Voltage.

#### Trim Up - Increase Output Voltage

With an external resistor ( $Radj\_up$ ) connected between the SENSE(+) and TRIM pins, the output voltage set point ( $V_{O,adj}$ ) increases (see Figure 14).

The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta\%$ .

#### For output voltages: $V_{O,nom} = 48V$

Without -T Option
$R_{adj\_up} = \left[ \frac{V_{O,nom} \times (100 + \Delta\%)}{1.225 \times \Delta\%} - \frac{(100 + (2 \times \Delta\%))}{\Delta\%} \right] k\Omega$
With –T Option
$R_{adj\_up} = \left(\frac{27122}{\Delta\%} + 15.12\right) k\Omega$
Where,
$\Delta\% = \left  \frac{V_{desired} - V_{o, nom}}{V_{o, nom}} \right  \times 100$
V <sub>desired</sub> = Desired output voltage set point (V).

# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

## **Feature Description (continued)**

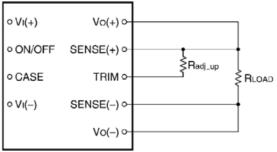


Figure 14. Circuit Configuration to Increase Output Voltage.

The voltage between the Vo(+) and Vo(-) terminals must not exceed the minimum output overvoltage shut- down value indicated in the Feature Specifications table. This limit includes any increase in voltage due to remote- sense compensation and output voltage set-point adjustment (trim). See Figure 11.

Although the output voltage can be increased by both the remote sense and by the trim, the maximum increase for the output voltage is not the sum of both.

The maximum increase is the larger of either the remote sense or the trim.

The amount of power delivered by the module is defined as the voltage at the output terminals multiplied by the output current. When using remote sense and trim, the output voltage of the module can be increased, which the same output current would increase the power output of the module. Care should be taken to ensure that the maximum output power of the module remains at or below the maximum rated power.

#### Examples:

To trim down the output of a nominal 48V module, without -T option, to 40V

$$\Delta\% = \left| \frac{48V - 40V}{48V} \right| \times 100$$

$$\Delta\% = 16.7\%$$

$$R_{adj\_down} = \left( \frac{100}{16.7} - 2 \right) k\Omega$$

To trim up the output of a nominal 48V module, without –T option. to 52.8V

$$\begin{split} \Delta\% &= \left| \frac{52.8V - 48V}{48V} \right| \times 100 \\ \Delta\% &= 10\% \\ R_{adj\_up} &= \left[ \frac{48 \times (100 + 10)}{1.225 \times 10} - \frac{(100 + (2 \times 10))}{10} \right] k\Omega \\ R_{adj\_up} &= 419.0k\Omega \end{split}$$

#### **Active Voltage Programming**

For the JRCW450Ux a Digital-Analog converter (DAC), capable of both sourcing and sinking current can be used to actively set the output voltage, as shown in Figure 15. The value of  $R_{\rm G}$  will be dependent on the voltage step and range of the DAC and the desired values for trim-up and trim-down  $\Delta\%$ . Please contact your GE technical representative to obtain more details on the selection for this resistor.

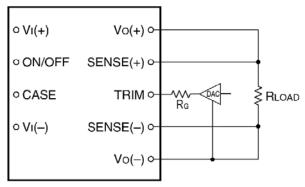


Figure 15. Circuit Configuration to Actively Adjust the Output Voltage.

#### **Over Temperature Protection**

The JRCW450U module provides a non-latching over temperature protection. A temperature sensor monitors the operating temperature of the converter. If the reference temperature,  $T_{\rm REF\,1}$ , (see Figure 16) exceeds a threshold of 115 °C (typical), the converter will shut down and disable the output. When the base plate temperature has decreased by approximately 1-2 °C the converter will automatically restart.

#### **Tunable Loop**

The JRCW0450U-T modules have a new feature that optimizes transient response of the module called Tunable Loop.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop is implemented by connecting a series R-C between the SENSE(+) and TRIM pins of the module, as shown in Fig. 16. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

## JRCW450U Orca Series: DC-DC Converter Power Modules

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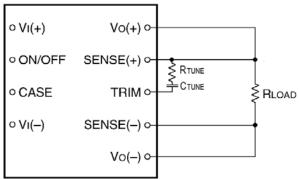


Figure 16. Circuit diagram showing connection of  $R_{\text{TUNE}}$  and  $C_{\text{TUNE}}$  to tune the control loop of the module.

Table 1 shows the recommended values of R<sub>TUNE</sub> and C<sub>TUNE</sub> for different values of ceramic output capacitors up to  $8000\mu F$  that might be needed for an application to meet output ripple and noise requirements.

Table 1. General recommended values of of  $R_{TUNE}$  and  $C_{TUNE}$  for  $V_{out}$ =48V and various external ceramic capacitor combinations.

C <sub>out</sub> (µF)	1100	2200	4400	6600	8800
ESR (mΩ)	60	30	15	10	7.5
R <sub>TUNE</sub>	TBD	TBD	TBD	TBD	TBD
C <sub>TUNE</sub>	TBD	TBD	TBD	TBD	TBD

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

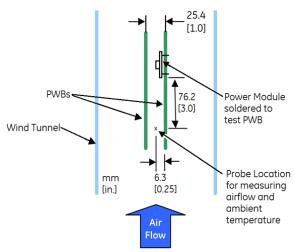
#### **Thermal Considerations**

The power modules operate in a variety of thermal environments; however, sufficient cooling should be provided to help ensure reliable operation of the unit. Heat-dissipating components inside the unit are thermally coupled to the case. Heat is removed by conduction, convection, and radiation to the surrounding environment. Proper cooling can be verified by measuring the case temperature. Peak temperature ( $T_{\text{REF}}$ ) occurs at the position indicated in Figure 16.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability.

The thermal data presented here is based on physical measurements taken in a wind tunnel, using automated thermo-couple instrumentation to monitor key component temperatures: FETs, diodes, control ICs, magnetic cores, ceramic capacitors, opto-isolators, and module pwb conductors, while controlling the ambient airflow rate and

temperature. For a given airflow and ambient temperature, the module output power is increased, until one (or more) of the components reaches its maximum derated operating temperature, as defined in IPC-9592. This procedure is then repeated for a different airflow or ambient temperature until a family of module output derating curves is obtained.



For reliable operation with Vin=48V this temperature should no texceed 100°C at either  $T_{\text{REF}\,1}$  or  $T_{\text{REF}\,2}$ , or 130 °C at  $T_{\text{REF}\,3}$  for applications using forced convection airflow without heat sink, or in cold plate applications. The temperatures at either  $T_{\text{REF}\,1}$  or  $T_{\text{REF}\,2}$  should not exceed 90°C, when using a 1in. heat sink in forced convection airflow. The output power of the module should not exceed the rated power for the module as listed in the ordering Information table. Although the maximum  $T_{\text{REF}}$  temperature of the power modules is discussed above, you can limit this temperature to a lower value for extremely high reliability.

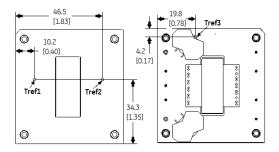


Figure 16. Case ( $T_{\text{REF}}$ ) Temperature Measurement Location (top view).

# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

## **Thermal Considerations (continued)**

#### **Thermal Derating**

Thermal derating is presented for different applications in Figure 17, 18 and 19. The JRCW450U module is mounted in a traditional open chassis or cards with forced air flow. The module is cooled by heat removal into a forced airflow that passes through the interior of the module and over the top base plate and/or attached heat sink. Conduction cooled thermal derating is presented in Figure 20.

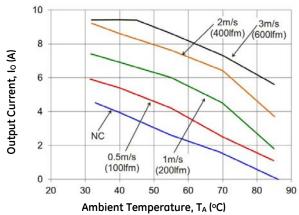


Figure 17. Derating Output Current vs. local Ambient temperature and Airflow, No Heat sink, Vin=48V, airflow from Vi(-) to Vi(+).

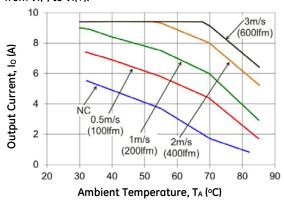


Figure 18. Derating Output Current vs. local Ambient temperature and Airflow, 0.5" Heat sink, Vin=48V, airflow from Vi(-) to Vi(+).

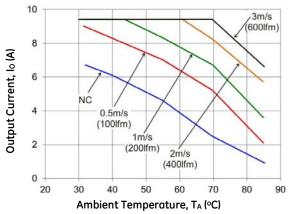


Figure 19. Derating Output Current vs. local Ambient temperature and Airflow, 1.0" Heat sink, Vin=48V, airflow from Vi(-) to Vi(+).

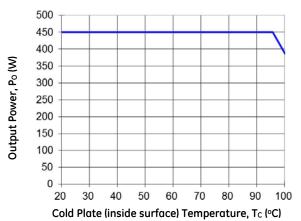


Figure 20. Derating Output Power in conduction cooling (cold plate) applications, Vin=48V.

# JRCW450U Orca Series; DC-DC Converter Power Modules

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#### **Layout Considerations**

The JRCW450U power module series are constructed using a single PWB with integral base plate; as such, component clearance between the bottom of the power module and the mounting (Host) board is limited. Avoid placing copper areas on the outer layer directly underneath the power module.

# Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to GE Board Mounted Power Modules: Soldering and Cleaning Application Note.

# Through-Hole Lead-Free Soldering Information

The RoHS-compliant through-hole products use the SAC (Sn/Ag/Cu) Pb-free solder and RoHS-compliant components. They are designed to be processed through single or dual wave soldering machines. The pins have a RoHS-compliant finish that is compatible with both Pb and Pb-free wave soldering processes. A maximum preheat rate of 3°C/s is suggested. The wave preheat process should be such that the temperature of the power module board is kept below 210°C. For Pb solder, the recommended pot temperature is 260°C, while the Pb-free solder pot is 270°C max. The JRCW450U cannot be processed with paste-through-hole Pb or Pb-free reflow process. If additional information is needed, please consult with your GE representative for more details.

# JRCW450U Orca Series; DC-DC Converter Power Modules

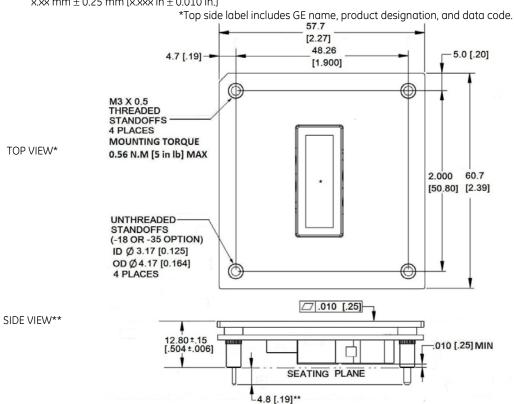
36-75 Vdc Input; 48.0Vdc Output; 450W Output

## Mechanical Outline for Through-Hole Module

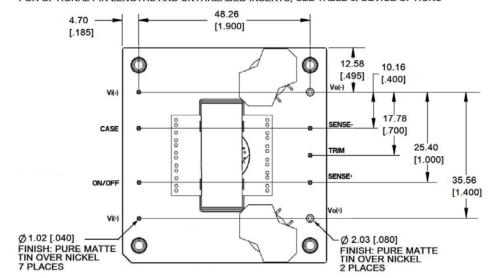
Dimensions are in millimeters and [inches].

Tolerances: x.x mm  $\pm$  0.5 mm [x.xx in.  $\pm$  0.02 in.] (Unless otherwise indicated)

x.xx mm  $\pm$  0.25 mm [x.xxx in  $\pm$  0.010 in.]



3.68 [.145] -35 OPTION \*\*FOR OPTIONAL PIN LENGTHS AND UNTHREADED INSERTS, SEE TABLE 3, DEVICE OPTIONS



# **BOTTOM VIEW**

Pin	Description
1	Vin (+)
2	On/Off
3	Baseplate
4	Vin (-)
5	Vout (-)
6	Sense (-)
7	Trim
8	Sense (+)
9	Vout (+)

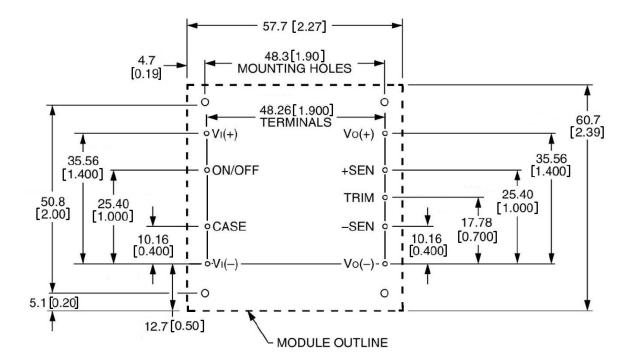
# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

## Recommended Pad Layout for Through Hole Module

Dimensions are in millimeters and [inches].

Tolerances: x.x mm  $\pm$  0.5 mm [x.xx in.  $\pm$  0.02 in. ] (Unless otherwise indicated) x.xx mm  $\pm$  0.25 mm [x.xxx in  $\pm$  0.010 in. ]



# JRCW450U Orca Series; DC-DC Converter Power Modules

36-75 Vdc Input; 48.0Vdc Output; 450W Output

## **Ordering Information**

Please contact your GE Sales Representative for pricing, availability and optional features.

Table 2. Device Code

Input Voltage	Output Voltage	Output Current	Efficiency	Connector Type	Product codes	Comcodes
48V (36-75Vdc)	48V	9.4A	94%	Through hole	JRCW450U641Z	CC109168992
48V (36-75Vdc)	48V	9.4A	94%	Through hole	JRCW450U64-18Z	150022105
48V (36-75Vdc)	48V	9.4A	94%	Through hole	JRCW450U64-35Z	150034270
48V (36-75Vdc)	48V	9.4A	94%	Through hole	JRCW450U641-18Z	150021936
48V (36-75Vdc)	48V	9.4A	94%	Through hole	JRCW450U641-TZ	CC109168984
48V (36-75Vdc)	48V	9.4A	94%	Through hole	JRCW450U64-18TZ	CC109172838

#### Table 3. Device Options

	Characteristic	Character and Position	Definition
Ratings	Form Factor	J	J = Half Brick
	Family Designator	RC	RC = Orca Family
	Input Voltage	w	<b>W</b> = Wide Range, 36V-75V
	Output Power	450	450 = 450 Watts Maximum Output Power
	Output Voltage	U	U = 48.0V nominal
	Pin Length	6 8	Omit = Default Pin Length shown in Mechanical Outline Figures 6 = Pin Length: 3.68 mm ± 0.25mm, (0.145 in. ± 0.010 in.) 8 = Pin Length: 2.79 mm ± 0.25mm, (0.110 in. ± 0.010 in.)
Options	Action following Protective Shutdown	4	Omit = Latching Mode 4 = Auto-restart following shutdown (Overcurrent/Overvoltage)
	On/Off Logic	1	Omit = Positive Logic  1 = Negative Logic
	Customer Specific	xv 35	XY = Customer Specific Modified Code, Omit for Standard Code 35 = Unthreaded insert standoffs, 4 places, and Uncut Pin length = 6 Option
	Mechanical Features	18	Omit = M3 x 0.5 threaded heat sink insert standoffs, 4 places  18 = Unthreaded insert standoffs, 4 places
	Tunable Loop™	Т	Internal compensation network optimized for Tunable Loop™ applications
	RoHS		Omit = RoHS 5/6, Lead Based Solder Used Z = RoHS 6/6 Compliant, Lead free

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